



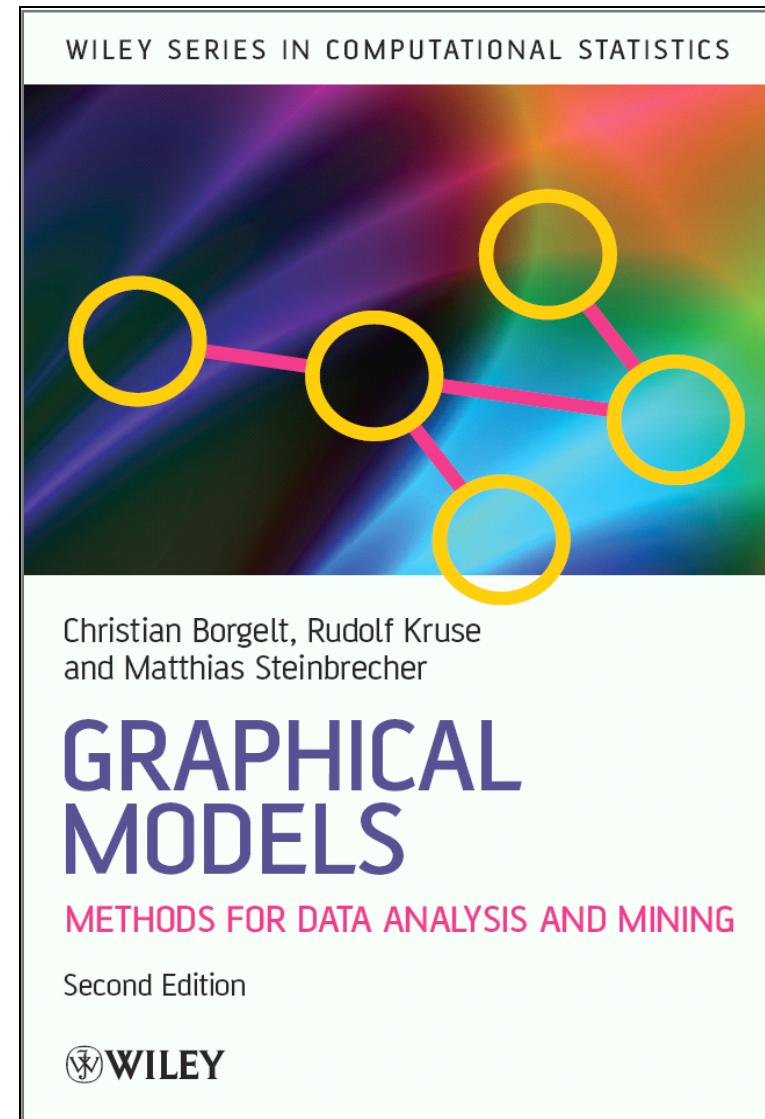
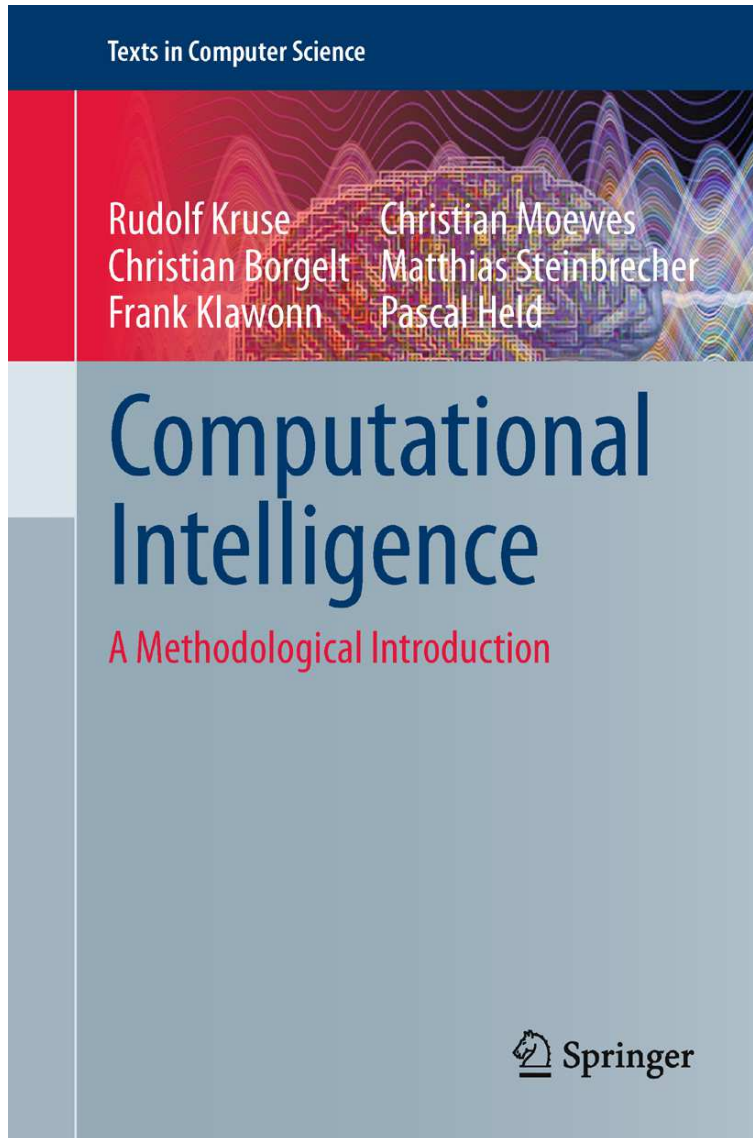
Bayesian Networks

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Books about the course



<http://www.computational-intelligence.eu/>

Human Expert

A human *expert* is a specialist for a specific differentiated application field who creates solutions to customer problems in this respective field and supports them by applying these solutions.

Requirements

- Formulate precise problem scenarios from customer inquiries
- Find correct and complete solution
- Understandable answers
- Explanation of solution
- Support the deployment of solution

Knowledge Based Systems (2)

“Intelligent” System

An intelligent system is a program that models the knowledge and inference methods of a human expert of a specific field of application.

Requirements for construction:

- Knowledge Representation
- Knowledge Acquisition
- Knowledge Modification

Qualities of Knowledge

In most cases our knowledge about the present world is

incomplete/missing (knowledge is not comprehensive)

- e. g. “I don’t know the bus departure times for public holidays because I only take the bus on working days.”

vague/fuzzy/imprecise (knowledge is not exact)

- e. g. “The bus departs roughly every full hour.”

uncertain (knowledge is unreliable)

- e. g. “The bus departs probably at 12 o’clock.”

We have to decide nonetheless!

Reasoning under Vagueness

Reasoning with Probabilities

... and Cost/Benefit

Example

Objective: *Be at the university at 9:15 to attend a lecture.*

There are several plans to reach this goal:

- P_1 : Get up at 8:00, leave at 8:55, take the bus at 9:00 ...
- P_2 : Get up at 7:30, leave at 8:25, take the bus at 8:30 ...
- ...

All plans are *correct*, but

- they imply different *costs* and different *probabilities* to *actually* reach that goal.
- P_2 would be the plan of choice as the lecture is important and the success rate of P_1 is only about 80–95%.

Question: *Is a computer capable of solving these problems involving uncertainty?*

Uncertainty and Facts

Example:

We would like to support a robot's localization by fixed landmarks.
From the presence of a landmark we may infer the location.

Problem:

Sensors are imprecise!

- We cannot conclude definitely a location simply because there was a landmark detected by the sensors.
- The same holds true for undetected landmarks.
- Only probabilities are being increased or decreased.

Degrees of Belief

We (or other agents) are only believing facts or rules to some extent.

One possibility to express this *partial belief* is by using *probability theory*.

“The agent believes the sensor information to 0.9” means:

In 9 out of 10 cases the agent trusts in the correctness of the sensor output.

Probabilities gather the “uncertainty” that originates due to ignorance.

Probabilities \neq Vagueness/Fuzziness!

- The predicate “large” is fuzzy whereas “This might be Peter’s watch.” is uncertain.

Rational Decisions under Uncertainty

Choice of several *actions* or *plans*

These may lead to different results with different *probabilities*.

The *actions* cause different (possibly subjective) *costs*.

The *results* yield different (possibly subjective) *benefits*.

It would be rational to choose that action that yields the largest total benefit.

Decision Theory = Utility Theory + Probability Theory

Decision-theoretic Agent

input perception

output action

- 1: $K \leftarrow$ a set of probabilistic beliefs about the state of the world
- 2: calculate updated probabilities for current state based on available evidence including current percept and previous action
- 3: calculate outcome probabilities for actions, given action descriptions and probabilities of current states
- 4: select action A with highest expected utility given probabilities of outcomes and utility information
- 5: **return** A

Decision Theory: An agent is rational if and only if it chooses the action yielding the largest utility averaged over all possible outcomes of all actions.